## Spatter-resistance type proximity sensor

#### ■ Features

- •Coated with teflon against thermal resistance (Prevention of malfunction due to spatter)
- •Improvede the noise resistance with dedicated IC
- •Integrated surge protection circuit
- •Integrated overload & short protection circuit (DC 2-wire, 3-wire type)
- •Integrated reverse polarity protection circuit (DC 3-wire type)
- •Red LED status indication
- •Protection structure IP67 (IEC standard)
- •Replaceable for spatter-resistance type limit switches







#### ■The characteristic of spatter-resistance type

The hot arc from arc welding machine is adhesive even with metals or plastics.

Therefore, normal proximity sensor might have malfunction even though there are no sensing object if the arcs are put on the sensing surface. The arcs are not adhered on the sensing part of the spatter-resistance type proximity sensor as the part is coated with teflon against thermal resistance.

Also, the protection cover sold optionally has the same function.

### Specifications

## ◆DC 2-wire type

Model						PRAWT30-10DO PRAWT30-10DC
Sensing distance	2mm	±10%	5mm ±10% 10i		10mr	n ±10%
Hysteresis	Max. 10% of sensing distance					
Standard sensing target	12×12×1mm(Iron)		18×18×1mm(Iron)		30×30×1mm(Iron)	
Setting distance	0 to	1.4mm	0 to 3.5mm		0 to 7mm	
Power supply (Operating voltage)	12-24VDC (10-30VDC)					
Leakage current	Max. 0.6mA					
Response frequency(*1)	1.5	ōkHz	50	00Hz	4	100Hz
Residual voltage	Max. 3.5V					
Affection by Temp.	±10% Max. for sensing distance at +20℃ within temperature range of -25 to 70℃					
Control output	2 to 100mA					
Insulation resistance	Min. 50MΩ (at 500VDC megger)					
Dielectric strength	1500VAC 50/60Hz for 1 minute					
Vibration	1mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours					
Shock	500m/s² (50G) in X, Y, Z direction for 3 times					
Indicator	Output operation indicator(Red LED)					
Ambient temperature	-25 to 70℃ (at non-freezing status)					
Storage temperature	-30 to 80℃ (at non-freezing status)					
Ambient humidity	35 to 95%RH					
Protection circuit	Surge protection circuit, overload & short protection circuit					
Protection	IP67 (IEC standard)					
Cable	$\phi$ 4×2P, 2m $\phi$ 5×2P, 2m					
Approval	CE					
Unit weight	Approx. 63g	Approx. 45g	Approx. 122g	Approx. 65g	Approx. 181g	Approx. 130g

**<sup>\*\*(\*1)</sup>** The response frequency is the average value. The standard sensing target is used and the width is set as 2 times of the standard sensing target, 1/2 of the sensing distance for the distance.

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<sup>\*\*</sup>IEC standard item is available and add "-I" to the end of model. Ex)PRAWT12-2DO-I

# Cylindrical Spatter-Resistance Type

## **■**Specifications

## ●DC 3-wire type

Model	PRA12-2DN PRA12-2DP PRA12-2DN2 PRA12-2DP2	PRA18-5DN PRA18-5DP PRA18-5DN2 PRA18-5DP2	PRA30-10DN PRA30-10DP PRA30-10DN2 PRA30-10DP2		
Sensing distance	2mm ±10%	5mm ±10%	10mm ±10%		
Hysteresis	Max. 10% of sensing distance				
Standard sensing target	$12 \times 12 \times 1$ mm (Iron)	18×18×1mm(Iron)	$30 \times 30 \times 1$ mm(Iron)		
Setting distance	0 to 1.4mm	0 to 3.5mm	0 to 7mm		
Power supply (Operating voltage)	12-24VDC (10-30VDC)				
Current consumption	Max. 10mA				
Response frequency(*1)	1.5kHz	500Hz	400Hz		
Residual voltage	Max. 1.5V				
Affection by Temp.	±10% Max. for sensing distance at +20℃ within temperature range of -25 to 70℃				
Control output	Max. 200mA				
Insulation resistance	Min. 50MΩ (at 500VDC megger)				
Dielectric strength	1500VAC 50/60Hz for 1 minute				
Vibration	1mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours				
Shock	500m/s <sup>2</sup> (50G) in X, Y, Z direction for 3 times				
Indicator	Output operation indicator(Red LED)				
Ambient temperature	-25 to 70℃ (at non-freezing status)				
Storage temperature	-30 to 80℃ (at non-freezing status)				
Ambient humidity	35 to 95%RH				
Protection circuit	Surge protection circuit, reverse polarity proteciton circuit, overload & short protection circuit				
Protection	IP67 (IEC standard)				
Cable	φ 4×3P, 2m φ 5×3P, 2m				
Approval	(€				
Unit weight	Approx. 70g	Approx. 119g	Approx. 184g		

<sup>\*(\*1)</sup> The response frequency is the average value. The standard sensing target is used and the width is set as 2 times of the standard sensing target, 1/2 of the sensing distance for the distance.

## ◆AC 2-wire type

Model	PRA12-2AO PRA12-2AC	PRA18-5AO PRA18-5AC	PRA30-10AO PRA30-10AC		
Sensing distance	2mm ±10%	5mm ±10%	10mm ±10%		
Hysteresis	Max. 10% of sensing distance				
Standard sensing target	12×12×1mm(Iron)	18×18×1mm(Iron)	30×30×1mm(Iron)		
Setting distance	0 to 1.4mm	0 to 3.5mm	0 to 7mm		
Power supply (Operating voltage)	100-240VAC (85-264VAC)				
Leakage current	Max. 2.5mA				
Response frequency(*1)	20Hz				
Residual voltage	Max. 10V				
Affection by Temp.	$\pm 10\%$ Max. for sensing distance at $\pm 20\%$ within temperature range of $\pm 25$ to $50\%$				
Control output	5 ~ 150mA 5 ~ 200mA				
Insulation resistance	Min. 50MΩ (at 500VDC megger)				
Dielectric strength	2500VAC 50/60Hz for 1 minute				
Vibration	1mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours				
Shock	500m/s <sup>2</sup> (50G) in X, Y, Z direction for 3 times				
Indicator	Output operation indicator(Red LED)				
Ambient temperature	-25 to 70°C (at non-freezing status)				
Storage temperature	-30 to 80℃ (at non-freezing status)				
Ambient humidity	35 to 95%RH				
Protection circuit	Surge protection circuit, overload & short protection circuit				
Protection	IP67 (IEC standard)				
Cable	φ 4×2P, 2m	ø 5×2P, 2m			
Approval	C€				
Unit weight	Approx. 66g	Approx. 130g	Approx. 185g		

<sup>\*(\*1)</sup> The response frequency is the average value. The standard sensing target is used and the width is set as 2 times of the standard sensing target, 1/2 of the sensing distance for the distance.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

#### (D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

> (J) Counter

(K) Timer

Panel meter (M) Tacho/ Speed/ Pulse meter

(N) Display unit

Sensor controller

(P) Switching power supply

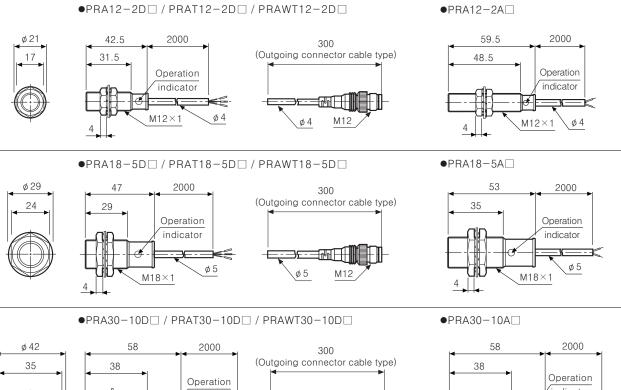
(Q) Stepping motor & Driver & Controller

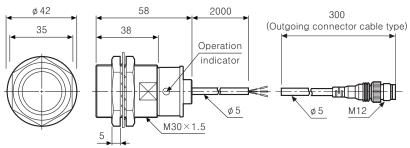
Graphic/ Logic panel

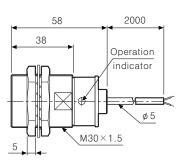
Field network device

Production stoppage models & replacement



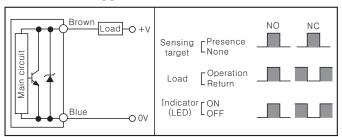




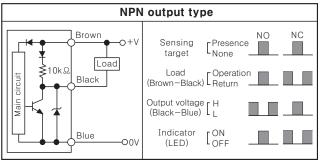


#### **■**Control output diagram

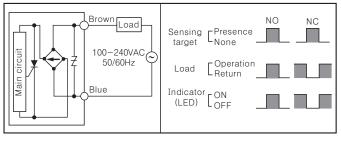
#### ○DC 2-wire type

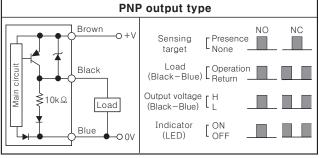


#### ODC 3-wire type



#### OAC 2-wire type



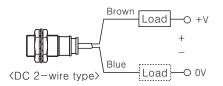


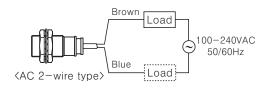
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## Cylindrical Spatter-Resistance Type

#### ■ Connections

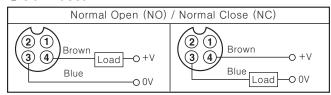
## ○DC 2-wire standard type / AC 2-wire type





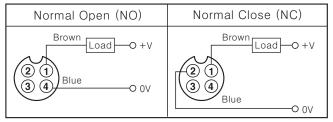
- \*When using DC 2-wire and AC 2-wire type, a load must be connected before applying power; otherwise, components can be damaged.
- \*The load can be connected to either wire.

#### Connector



\*1, 2 are N · C(Not Connected) terminals

#### ODC 2-wire type(IEC standard type)

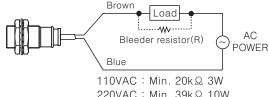


※②, ③ of NO Type and ③, ④ of NC Type are N·C(Not Connected) terminals.

## Proper usage

#### OIn case of the load current is small

●AC 2-wire type



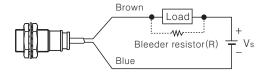
220VAC : Min. 39kΩ 10W

If the load current is under 5mA, please make sure the residual voltage is less than the return voltage of the load by connecting a bleeder resistor in parallel with the load as shown in the diagram.

$$R = \frac{V_S}{I} (\Omega) \quad P = \frac{V_S^2}{R} (W)$$

[ I:Action current of load, R:Bleeder resistance, P:Permissible power]

●DC 2-wire type



Please make the current on proximity sensor smaller than the return current of load by connecting a bleeder resistor in parallel.

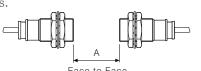
\*W value of Bleeder resistor should be bigger for proper heat dissipation.

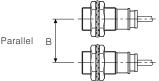
$$R = \frac{V_S}{Io-Ioff} (\Omega) \qquad P = \frac{V_S^2}{R} (W)$$

[Vs: Power supply, Io: Min. action current of proximity sensor Ioff: Return current of load, P: Number of Bleeder resistance watt]

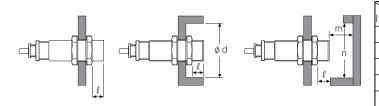
#### Mutual-interference & Influence by surrounding metals

When several proximity sensors are mounted close to one another a malfunction of th may be caused due to mutual interference. Therefore, be sure to provide a minimum distance between the two sensors as below chart indicates.





When sensors are mounted on metallic panel, you must prevent the sensors from being affected by any metallic object except target. Therefore, be sure to provide a minimum distance as below chart indicates.



Model Item	PRA□12-2□□	PRA□18-5□□	PRA□30−10□□
Α	12	30	60
В	24	36	60
l	0	0	0
ø d	12	18	30
m	6	15	30
n	18	27	45

electric sensor (B)

optic sensor

(A) Photo

Door/Area

(D) Proximity sensor

Pressure sensor

(F) Rotary encoder

Connector/ Socket

(H) Temp.

SSR/ controller

(J) Counter

Timer (L)

(K)

Tacho/ Speed/ Pulse

meter

meter

(N) Display unit

Sensor controller

Switching power supply

(Q) Stepping motor & Driver & Controlle (R)

Graphic/ Logic panel (S)

Field network device

Production stoppage models & replacement

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