Autonics

Motor Driver(2-Phase microstepping driver)

MD2U-MD20

M A N U A





Thank you very much for selecting Autonics products. For your safety, please read the following before using.

Caution for your safety

XPlease keep these instructions and review them before using this unit.

XPlease observe the cautions that follow;

⚠ Warning Serious injury may result if instructions are not followed.

△ Caution Product may be damaged, or injury may result if instructions are not followed.

XThe following is an explanation of the symbols used in the operation manual.

- 1. In case of using this unit with machinery (Ex: nuclear power control, medical equipment, ship, vehicle, train, airplane, combustion apparatus, safety device, crime/disaster prevention equipment, etc) which may cause damages to human life or property, it is required to install fail-safe device.
- It may cause serious human injury or damage to property.

 2. Installation, connection, operation, control, maintenance should be carried out by person
- who has been qualified.
- It may cause a fire, electric shock or human injury.
- 3. Please use DC power with reinforced insulating the primary and secondary part for the DC power product.
- It may give an electric shock.

 4. Please install this unit after considering counterplan against power failure.
- It may cause human injury or damage to product by releasing holding torque of motor.

 5. Do not use this unit outdoors or place where there are flammable, corrosive gas, water and too much vibration etc.
- It may cause a fire or give an electric shock. 6. Do not put finger or any object into this product
- It may cause a fire or give an electric shock.

 7. Do not disassemble and modify this unit, when it is required, please contact us.
- It may cause a fire or give an electric shock, damage to product 8. Please use the adjuster with insulated screw driver.
- It may give an electric shock.

⚠ Caution

- 1. Do not move, install, connect or inspect during the operation. It may give an electric shock
- Power input voltage must be used within rated specification and power line should be over than AWG 18(0.75mm²).
- It may cause a fire or give an electric shock. 3. Please check the connection before supplying the power.
- It may cause a fire or give an electric shock, damage to product.

 4. When connecting the unit with power, please install current breaker. It may cause a fire
- 5. Please turn off the power when power is failed.
- It may cause human injury or damage to product due to sudden movement when recovering power
- 6. Please supply power after checking control input signal.
- It may cause a burn due to high temperature in surface.
- 7. The emergency stop is needed during the operation.
 It may cause human injury or damage to product.
- 8. Please apply power after checking control input signal.

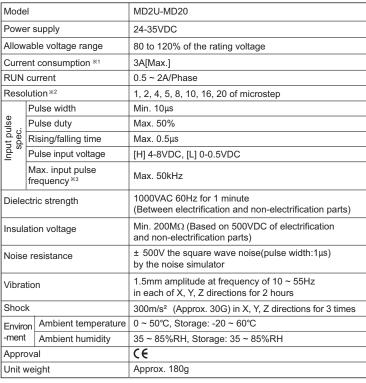
 It may cause human injury or damage to product by sudden movement.
- 9. Do not turn on the HOLD OFF signal input while it is maintaining vertical position. It may cause human injury or damage to product by releasing holding torque of motor.
- 10. Please install a safety device when it is required to remain the vertical position after turning off the power.
- It may cause human injury or damage to product by releasing holding torque of motor.

 11. Please check if HOLD OFF signal input is ON when it is required to set the output manually.
- It may cause human injury by sudden movement.

 12. Please stop this unit when mechanical problem occurred.
- It may cause a fire or human injury.

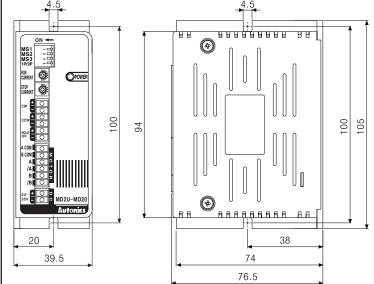
 13. Do not touch the terminal when measuring insulation resistance and testing insulation dielectric strength.
 It may give an electric shock.
- 14. Please observe rated specification.
 It may cause human injury, electric shock or damage to product.
- 15. In cleaning the unit, do not use water or an oil-based detergent. It may cause a fire or give an electric shock.
- 16. Please separate as industrial waste when disusing this unit.
- 17. Please use the designated 2-phase stepping motor in output part.
- XThe above specifications are changeable at anytime without notice.

Specifications



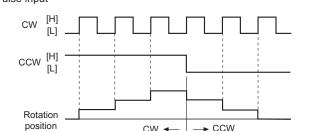
- ※1: Ambient temperature is 25°C and ambient humidity is 55%RH.
- X2: The max. value of RUN current is based on RMS value in accordance with frequency of running motor, peak power can be changed by load fluctuation. *3: It can be changed by pull-out frequency and max. slewing frequency range.
- XEnvironment resistance is rated at no freezing or condensation.

Dimensions

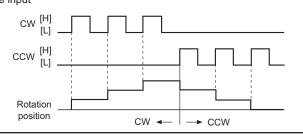


Time charts

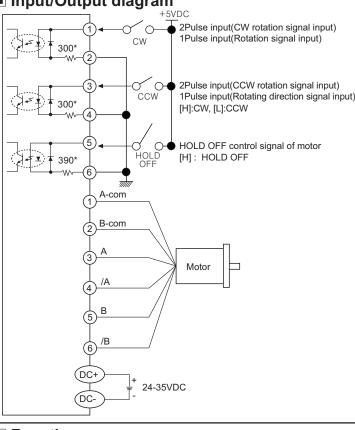
•1 Pulse input



•2 Pulse input



■ Input/Output diagram



Function

(Unit:mm)

Function switch

	No.	Name	Function	Switch position			
ON 1 2 3 4				ON			OFF
	1	MS1	Microstep set 1	MS1	MS2	MS3	Resolution
				ON	ON	ON	1(Full-step)
				ON	ON	OFF	2 division
	2	MS2	Microstep set 2	ON	OFF	ON	4 division
				ON	OFF	OFF	5 division
				OFF	ON	ON	8 division
	3	MS3	Microstep set 3	OFF	ON	OFF	10 division
				OFF	OFF	ON	16 division
				OFF	OFF	OFF	20 division
	4	1P/2P	Selectable RUN mode	1 Pulse method			2 Pulse method

Resolution Setting(MS1/ MS2/ MS3)

- 1. A switch to select micro step angle to drive a motor.
- 2. Microstepping is to make basic step angle of 2-phase motors (1.8°) divided into smaller angle according to setting values.
- 3. The formula for microstep angle is;

1.8° or 0.9° Rotation angle per pulse of 2-phase[°] = Resolution

4. It may cause step-out if resolution is changed while motor is running.

●1P / 2P

- 1. A switch to select pulse input type.
- 2. 1-pulse input mode
- CW: Operation command pulse input
- CCW: Rotation direction pulse input([H]: CW, [L]: CCW)
- 3. 2-pulse input mode

CW: CW direction rotation pulse input CCW: CCW direction rotation pulse input

●RUN current setting



- 1.RUN current is a phase current provided to 2-phase stepping
- 2.Be sure to set RUN current at the rated current or below. If not.
- it may cause heat generation, loss of torque or step-out. 3.RUN current setting range: 0.5 ~ 2.0A
- 4.RUN current setting : Measure the voltage by connecting a DC voltage meter to both CT+ and CT- terminals while the motor is running (Max. 150rpm).

Ex)Input Voltage(3V) X 2 / 3 = 2A(Motor's excitation current)

5. Adjust the RUN current in case severe heat generation occurs.

Be sure that torque decreasing may occur when adjusting the current.

6.RUN current setting value may have some deviation depending on motor's running

Note)Be sure to adjust RUN current while motor is running.

STOP current setting



- 1.Stop current is a phase current provided to 2-phase stepping motor at standstill.
- 2.A function to reduce the current in order to suppress the heat generation at motor standstill / Use variable resistance ratio within 0~100% of RUN current to set STOP current (Actual setting range is 20~70% of RUN current).
- Ex)If RUN current setting value is 2A and STOP current setting value is 0%, STOP current will be set to 0.4A. 3.STOP current setting value may have some deviation depending on resistance
- impedance of motor. 4.Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to

Note) Be sure to adjust STOP current while motor is at standstill.

Failure diagnosis and management

1. If motor does not rotate

- ①Check the connection of controller and driver and pulse input specification. (Voltage,
- ②Check the input pulse method and connected method is same
- (3) Check pulse and direction signal is connected correctly for 1P input.
- 2. If motor rotates as a reverse direction.
- ①Check input pulse connection of CW and CCW is correct for 2P input.
- ②In case of 1P input, it is CW rotation when the input is [H] in CCW and it is CCW rotation for [L].
- 3. If motor does not work properly.
- ①Check the connection of driver and motor.②Check the pulse input specification(VoltageUwidth) of driver.
- 3 Check output current for current adjusting SW and current for motor operation as correct.

Caution for using

1. Caution for signal input

- ①When using the 2 pulse input method, do not input CW and CCW at the same time, or it may cause malfunction.
- ②In case, the signal input supply is higher than rated supply expressed on the specification, please connect the additional resistance to external part. (Connect $3k\Omega$ of resistance when applying 24V of power)
- 2. Caution for setting the RUN and STOP current
- RUN current must be set under a rated current of the motor because motor emits heat too much when a RUN current is set over a rated current of the motor.
- Caution for wiring
 ①Use Twist pair(Over 0.2mm²) for the signal wire should be shorter than 2m. ②Please use an electric wire is thicker than the motor lead when lengthening the motor
- wire connection ③ Please leave a space over 10cm between a signal wire connection and power wire.
- 4. Caution for installation
- Office of the heat sink as close as possible to metal panels and place the unit in well-ventilated area in order to increase heat protection efficiency of heat sink.
- ②Heat generation may occur on drivers depending on installation environments. Place the unit with keeping the heat sink under 80°C.
- 5 Caution of using function switch

When the input switch is changed to 2P input method during the operation, it may be danger as the motor is rotated reversely. Please do not change the input signal method and resolution during the operation.

6. Motor vibration and noise can be occurred in specific frequency period. ①Motor vibration and noise can be lowered by change motor installation or attach

②Use the unit in a range without vibration and noise range by RUN speed adjustment or microstep.

Installation environment ①It shall be used indoor

@Altitude Max 2000m ③Pollution Degree 2 (4) Installation Category II

■ Photoelectric sensors

■ Fiber optic sensors

■ Panel meters

■ Display units

Timers

×It may cause malfunction if above instructions are not followed.

Major products

- Proximity sensors
- Area sensors
- Pressure sensors Counters
- Rotary encoders
- Power controllers Sensor controllers
- Door/Door side sensors
- Graphic/Logic panels
- Temperature controllers
- Tachometer/Pulse(Rate) meters
- Temperature/Humidity transducers
- Stepping motors/drivers/motion controllers
- Laser marking system(CO₂, Nd:YAG) Laser welding/soldering system

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The proposal of a product improvement

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